Grasp Planning toolbox in Choreonoid

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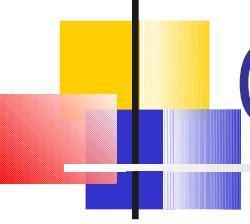
Grasp planning toolbox

- Plugins of Choreonoid

   (choreography for humanoid)

- Features
- Fast calculation for online processing
- Easy to operate

Chreonoid Features
- Easily extendable
- User customizable

System overview

Pick & place
Planner

RT moudles
(OpenRTM)
Vision module etc.

Grasp
planner

Path
planner

Geometry
feature
analysis

Connecter
with
RT modules

Choreonoid
Motion editor, Motion management, GUI base
Kinematics solver, Collision detection, Simulation
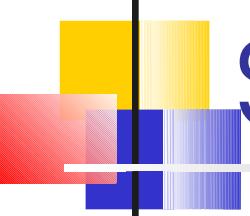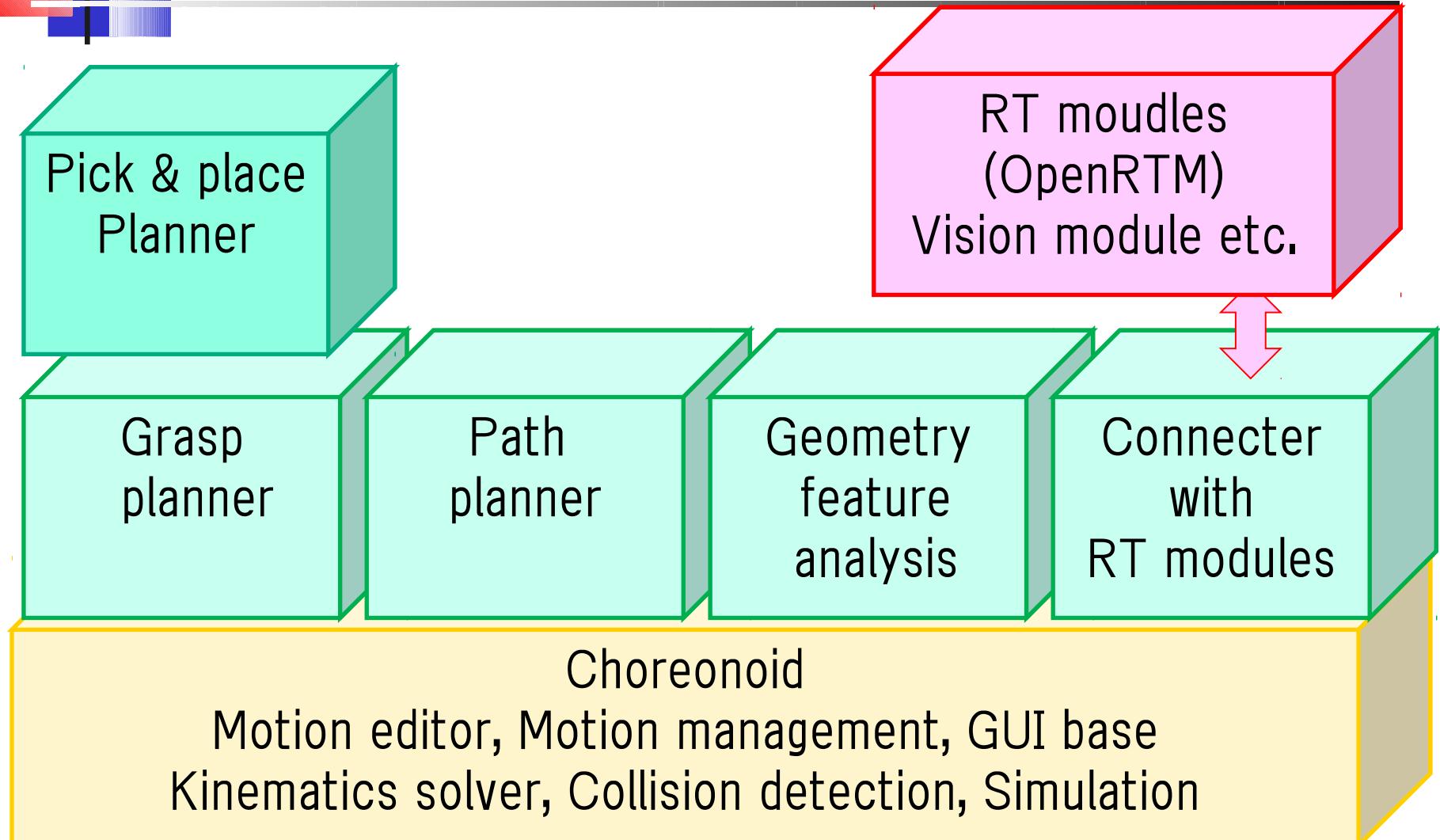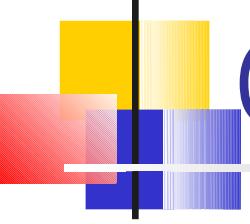
Grasp planning

SetObject
SetRobot
SetEnv
Grasp
Stop
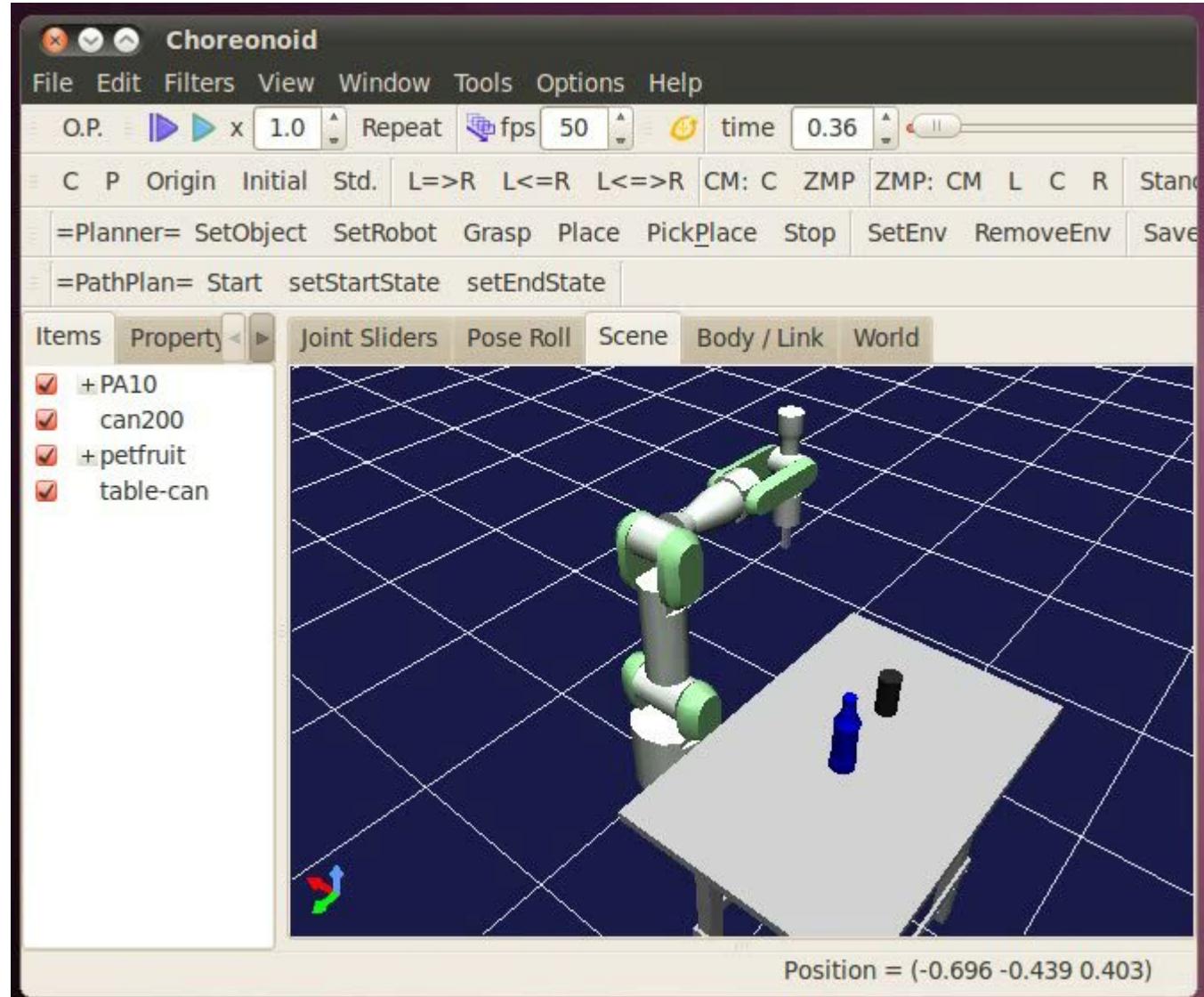
# Path planning
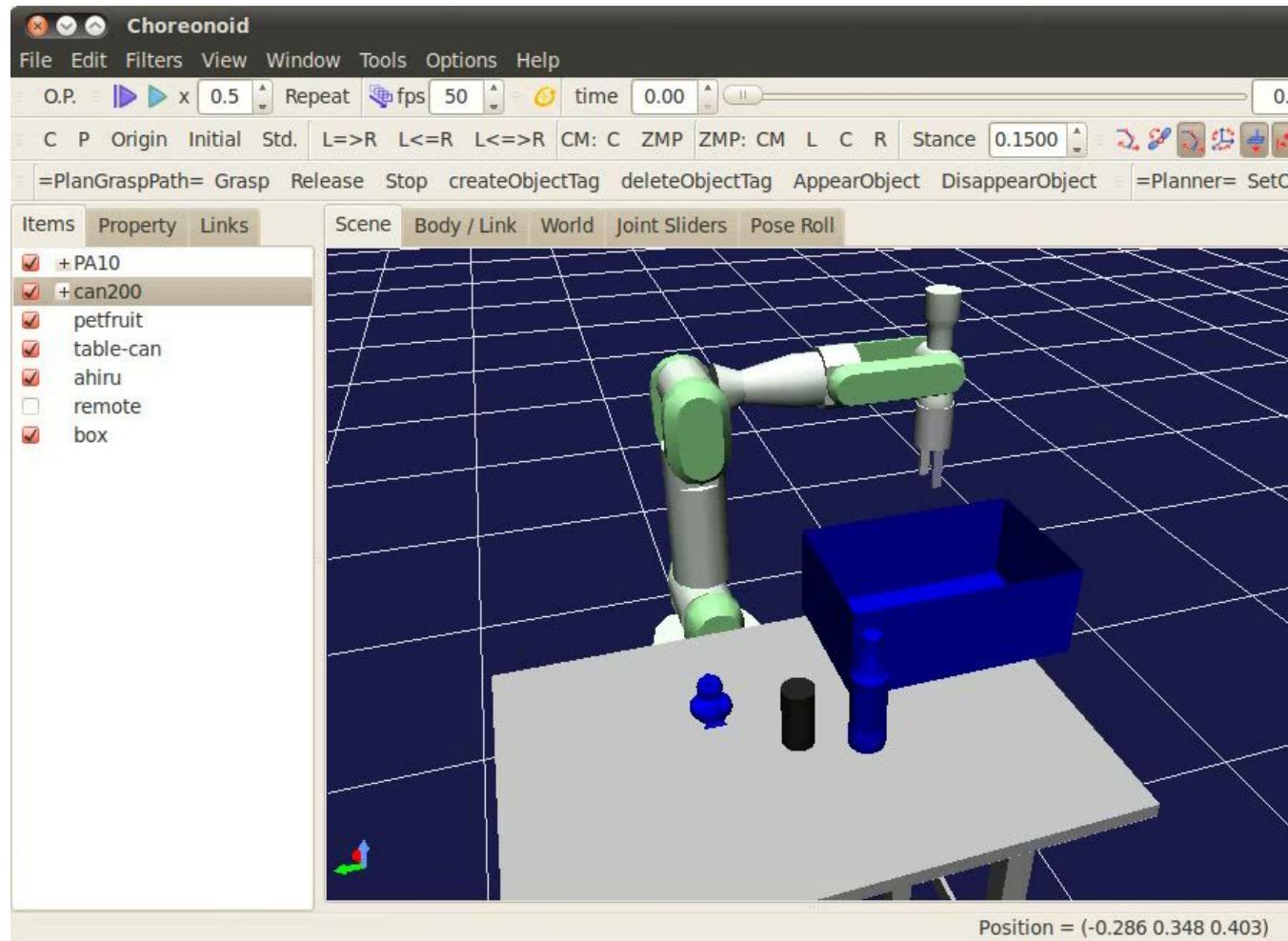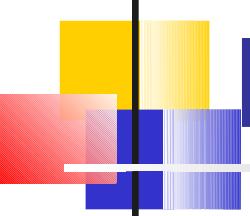
Pick and place planning
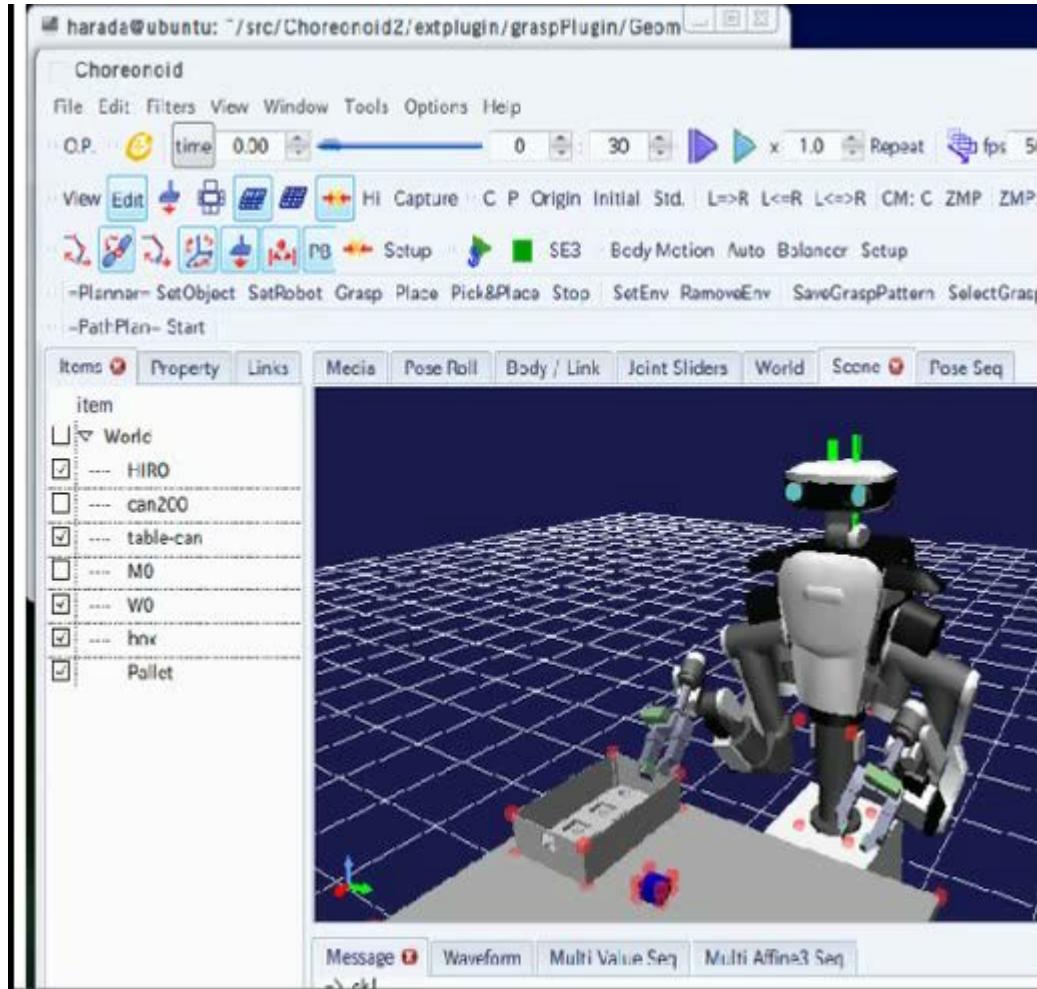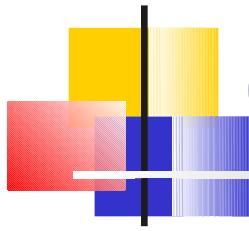
Geometry analysis
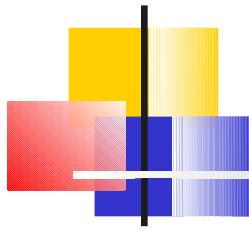
HIRO operation
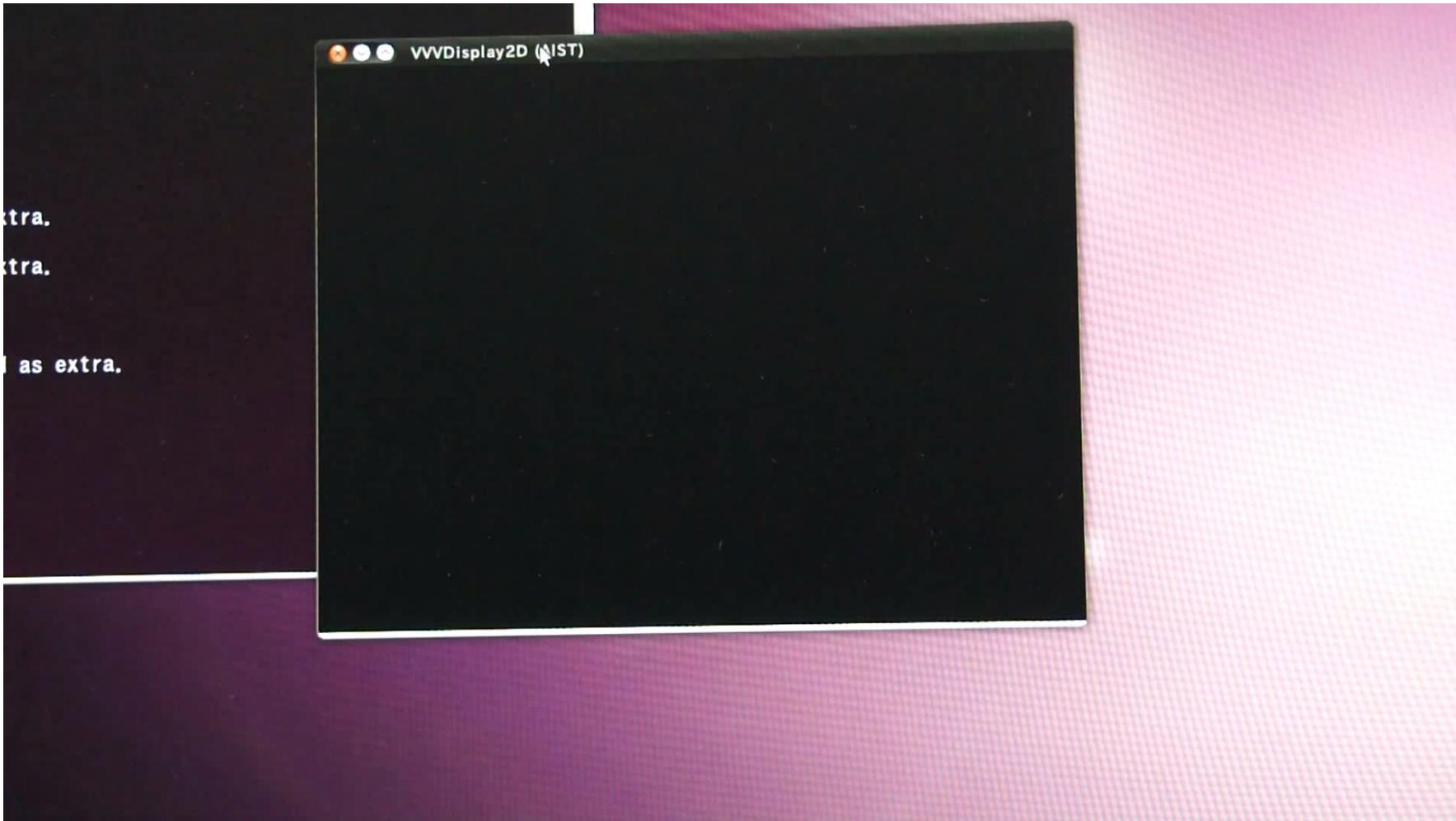
PA10 operation
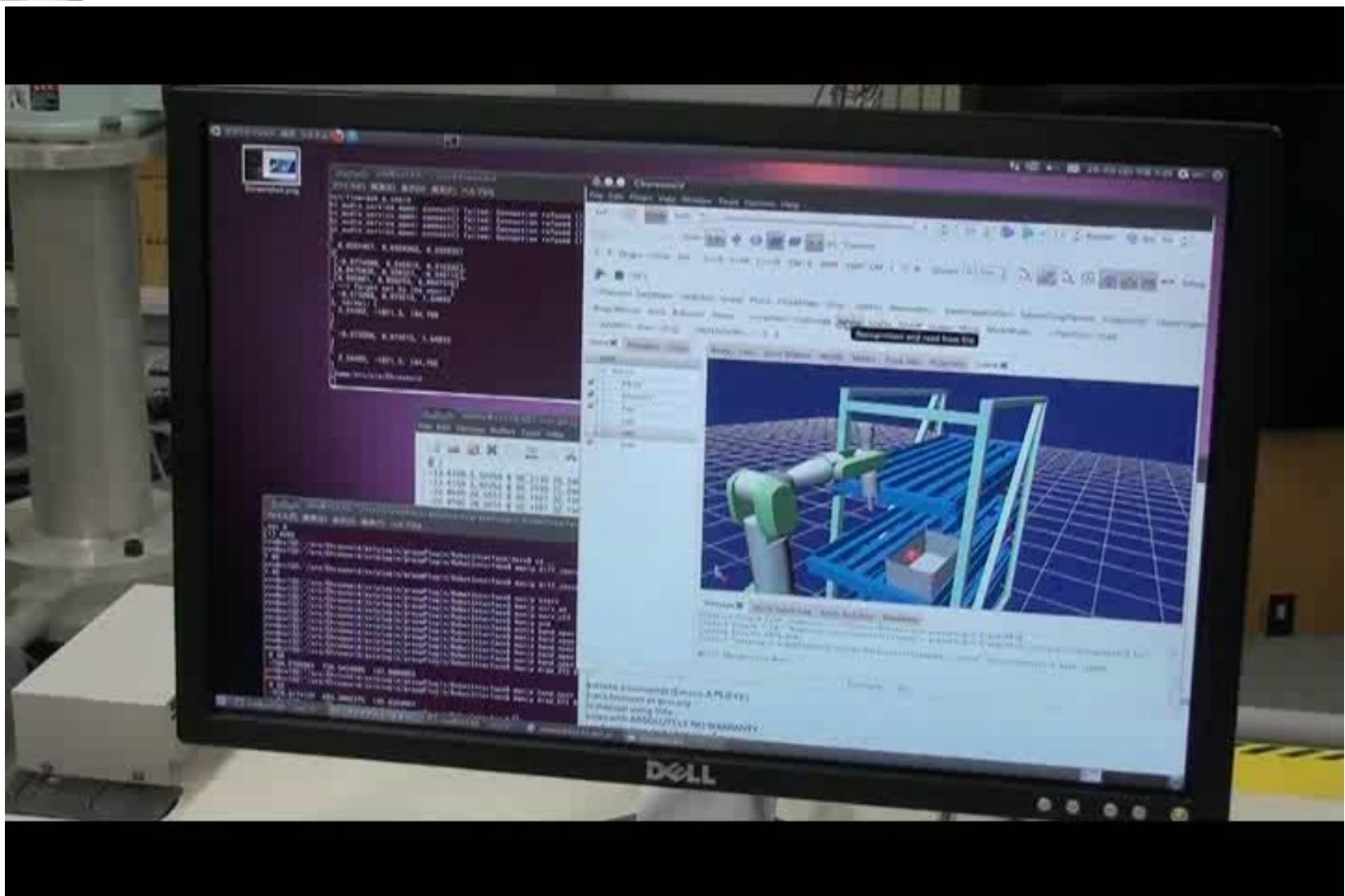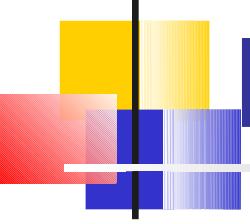
Robot models

- PA-10
- RH-1
- HRP-3P
- SmartPal
- Hiro
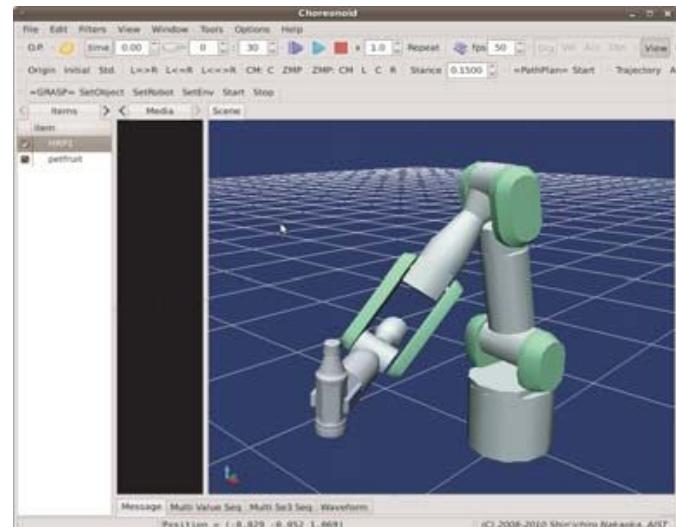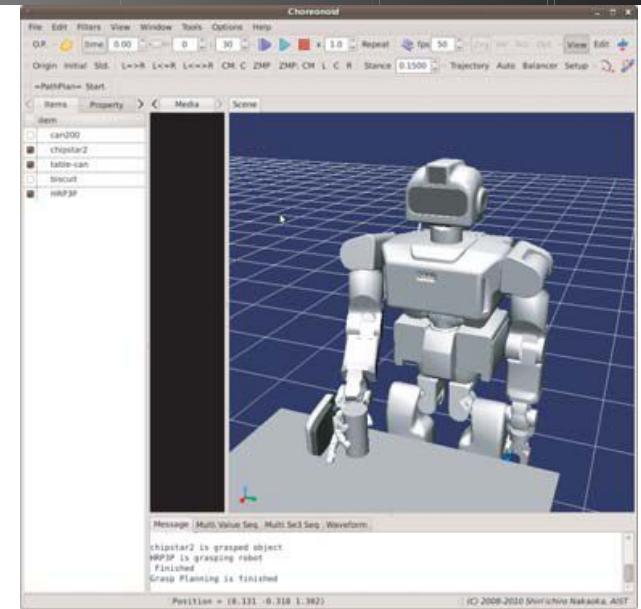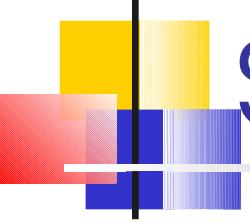
Summary

- Grasp planning toolbox
    - Fast calculation
    - Extendable framework

- Next steps
    - Grasp planner and simulator for soft finger contact
    - Intuitive GUI
    - Documetation